

## **DIGITAL MARINE CONTROL**

## **D-MaC**

**POWER MANAGEMENT** FOR MAIN ENGINES

#### **MV Canadian Venture**

**LOA.:** 222.5 m

Engine: 4 × Fairbanks Morse

Power: 4 × 1491 kW @ 750 RPM

CP Prop: 1 × KaMeWa

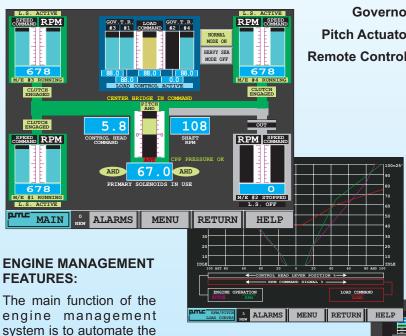
Governor: Woodward 828 / UA

Pitch Actuator: PMC Type 3310 PA-ER2

Remote Controls: PMC Electronic Two Station Remote Control System with:

## • Drop in propulsion control and instrumentation plates

- D-MaC utilizing a touch screen display with nonvolitile memory and no hard drives
- Electronic Speed Control / Load Sharing
- Electronic Pitch Control / **Load Control**
- Engine Management for propulsion



The sequence of adding engines to the plant includes interlocks and

engine start, run-up and clutch in sequence for multi-engine plants.

logic such as:

- Speed ramp
- Speed matching
- Clutch soft engage
- Soft loading
- Soft unloading

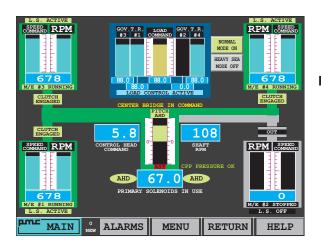




## **DIGITAL MARINE CONTROL**

# **D-MaC**

### **POWER MANAGEMENT** FOR MAIN ENGINES



### MV Stephen B. Roman

**LOA**.: 149 m

Engine: 4 × Fairbanks Morse

Power: 2 × 10 Cyl 1242 kW @ 750 RPM

2 × 8 Cyl 994 kW @ 750 RPM

CP Prop: 1 × KaMeWa

Governor: Woodward 828 / UA

Pitch Actuator: PMC Type 3310 PA-ER2

Remote Controls: PMC Electronic Two Station Remote Control System with:

• Drop in propulsion control

- and instrumentation plates
- D-MaC utilizing a touch screen display with nonvolitile memory and no hard drives
- Electric Shaft Control Heads
- Electronic Speed Control / **Load Sharing**
- Electronic Pitch Control / Load Control
- Engine Management for propulsion



